Encoders
magnetic Encoder, digital outputs,
3 channels, 256 - 4096 lines per revolution

Series IEH3-4096

<table>
<thead>
<tr>
<th>Lines per revolution</th>
<th>IEH3-256</th>
<th>IEH3-512</th>
<th>IEH3-1024</th>
<th>IEH3-2048</th>
<th>IEH3-4096</th>
</tr>
</thead>
</table>
| Frequency range, up to \(^1\) | \(f\) | 256 | 512 | 1 024 | 2 048 | 4 096 | kHz
| Signal output, square wave | \(2+1\) Index Channels |
| Supply voltage | \(U_{cc}\) | 4.5 ... 5.5 | V |
| Current consumption, typical \(^2\) | \(I_{cc}\) | typ. 25, max. 40 | mA |
| Output current, max. \(^3\) | \(I_{out}\) | 2.5 | mA |
| Index Pulse width \(^4\) | \(p_t\) | 90 ± 45 | 90 ± 65 | 90 ± 75 | 90 ± 45 | 90 ± 65 | 90 ± 75 | μs |
| Signal rise/fall time, max. \(C_{load} = 50 \text{ pF}\) | \(t_{r/f}\) | 0.05 / 0.05 |
| Inertia of sensor magnet | \(J\) | 0.11 |
| Operating temperature range | -40 ... +100 | °C |

\(^1\) Velocity (min\(^{-1}\)) = \(f\) (Hz) x 60/W
\(^2\) \(U_{cc}\) = 5 V: with unloaded outputs
\(^3\) \(U_{cc}\) = 5 V: low logic level < 0.4 V, high logic level > 4.5 V: CMOS- and TTL compatible
\(^4\) At 5 000 min\(^{-1}\)

For combination with Motor

Dimensional drawing A <L1 [mm]
1336 ... CXR - 123 47.5

Dimensional drawing B <L1 [mm]
1516 ... SR 18.2
1524 ... SR 26.2
1717 ... SR 19.4
1724 ... SR 26.4
2224 ... SR 26.6
2232 ... SR 34.6

Dimensional drawing C <L1 [mm]
1727 ... CXR - 123 38.2
1741 ... CXR - 123 52.2

Characteristics

These incremental encoders with 3 output channels, in combination with the FAULHABER Motors, are used for the indication and control of both shaft velocity and direction of rotation as well as for positioning.

The encoder is integrated in the DC-Micromotors SR-Series and extends the overall length by only 1.4 mm.

A segmented magnetic disc provides a magnetic field which is detected and further processed by an angle sensor.

The output signals of both channels consist of a square wave signal with 90° phase shift and up to 4096 impulses and an index impulse per motor revolution.

The encoder is available with different standard resolutions.

The supply voltage for the encoder and the DC-Micromotor as well as the two channel output signals are interfaced through a ribbon cable with connector.

Details for the DC-Micromotors and suitable reduction gearheads are on separate catalogue pages.

To view our large range of accessory parts, please refer to the “Accessories” chapter.
Circuit diagram / Output signals

Output circuit

Output signals
with clockwise rotation as seen from the shaft end

Connector information / Variants

<table>
<thead>
<tr>
<th>No.</th>
<th>Function</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>N.C.</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Motor - *</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>Motor + *</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>GND</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>Uoo</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>Channel B</td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>Channel A</td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>Channel I</td>
<td></td>
</tr>
</tbody>
</table>

*Note: DC-Micromotors series CXR have separate motor leads.

Connection Encoder

Cable
PVC-ribbon cable
8-AWG 28, 0.09 mm²

Connector
Molex PicoBlade
grid 1,25 mm

Full product description
Example: 1516T0065R IEH3-4096

Dimensional drawing A

Example of combination with 1336...CXR

IEH3-4096
For notes on technical data and lifetime performance refer to "Technical Information".

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