

Encoders

Optical Incremental Encoders

Features:
 32 to 1250 cycles per revolution
 2 or 3 Channels
 TTL Digital output

Series E2

| | | E2 | E2...I | |
|---|-----------------|---|------------|------------------|
| Cycles per revolution | N | 32 - 1 250 | 50 - 1 250 | |
| Signal output, square wave | | 2 | 2+1 index | channels |
| Supply voltage | V _{CC} | 4,5 to 5,5 | | V DC |
| Current consumption, typical (V _{CC} = 5 V DC) | I _{CC} | <500 (CPR) = 33 max. ≥500 (CPR) = 57 max. | | mA |
| Pulse width | P | 180 ± 45 | | °e |
| Index pulse width | P _o | 90 ± 30 | | °e |
| Phase shift, channel A to B | Φ | 90 ± 30 | | °e |
| Cycle | C | 360 ± 5,5 | | °e |
| Signal rise/fall time, typical | tr/tf | 110 / 35 | | ns |
| Frequency range ¹⁾ | f | up to 300 | | kHz |
| Inertia of code disc | J | 0,6 | | gcm ² |
| Operating temperature range | | - 40 to +100 | | °C |

¹⁾ Velocity (rpm) = f (Hz) x 60/N

| Encoder type | Cycles per revolution (CPR) for all motors | for combination with: |
|--------------------------------|--|--|
| 2 Channel E2-XXXX | 32' 50, 96, 100, 192, 200 250, 256, 360, 400, 500, 512 540, 720, 900, 1000, 1024, 1250 | DC Micro Motor series 2230, 2233, 2237, 2342, 2642, 2657 3242, 3257, 3272, 3557, 3863 |
| 3 Channel E2-XXXX... | | Brushless DC-Servomotors series 2036, 2057, 2444 3056, 3564 4490 |

*32 CPR not available with index

Note: XXXX = number of cycles per revolution

These incremental shaft encoders in combination with the FAULHABER DC micro motors are designed for indication and control of both, shaft velocity and direction of rotation as well as for positioning.

A LED source and lens system transmits collimated light through a low inertia mylar disc with machined aluminum hub, to give two channels with 90° phase shift.

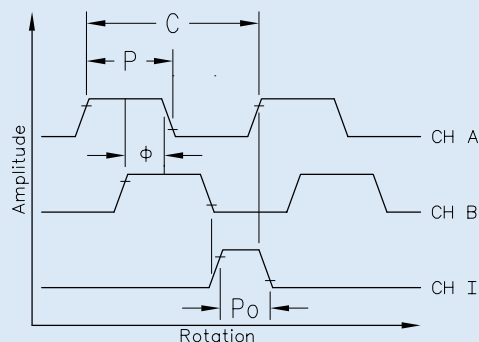
A body adapter is available to set orientation ± 15° some models available with thru shaft option.

The single 5 volt supply and the two or three channel digital output signals are interfaced with a 5-pin connector or 5-pin locking connector (sold separately).

Base and cover constructed of rugged 20% glass filled polycarbonate.

Ball bearings are recommended for continuous operation at low and high speeds and for elevated radial shaft load.

Details for the DC micro motors and suitable reduction gearheads are on separate catalog pages.



Output signals

- PINOUT
- 1 GND
 - 2 CH I
 - 3 CH A
 - 4 V_{CC}
 - 5 CH B

