

# DC-Micromotors

## 1 mNm

### Precious Metal Commutation

For combination with  
Gearheads:  
10/1, 12/3, 12/4, 12/5  
Encoders:  
30B

### Series 1224 ... S

	1224 N	006 S	012 S	015 S	
1 Nominal voltage	$U_N$	6	12	15	V
2 Terminal resistance	R	6,6	26,8	42,3	$\Omega$
3 Output power	$P_{2 \max}$	1,3	1,3	1,3	W
4 Efficiency, max.	$\eta_{\max}$	78	78	78	%
5 No-load speed	$n_0$	12 700	13 100	12 400	rpm
6 No-load current (with shaft $\varnothing$ 1 mm)	$I_0$	0,013	0,006	0,005	A
7 Stall torque	$M_H$	3,69	3,6	3,62	mNm
8 Friction torque	$M_R$	0,05	0,05	0,05	mNm
9 Speed constant	$k_n$	2 318	1 173	923	rpm/V
10 Back-EMF constant	$k_E$	0,431	0,852	1,084	mV/rpm
11 Torque constant	$k_M$	4,12	8,14	10,35	mNm/A
12 Current constant	$k_i$	0,243	0,123	0,097	A/mNm
13 Slope of n-M curve	$\Delta n / \Delta M$	3 713	3 862	3 771	rpm/mNm
14 Rotor inductance	L	65	250	450	$\mu$ H
15 Mechanical time constant	$\tau_m$	7	7	7	ms
16 Rotor inertia	J	0,18	0,18	0,18	gcm <sup>2</sup>
17 Angular acceleration	$\alpha_{\max}$	205	200	201	$\cdot 10^3$ rad/s <sup>2</sup>
18 Thermal resistance	$R_{th 1} / R_{th 2}$	22 / 45			K/W
19 Thermal time constant	$\tau_{w1} / \tau_{w2}$	6,5 / 392			s
20 Operating temperature range:					
– motor		-30 ... +85 (optional version	-30 ... +125)		$^{\circ}$ C
– rotor, max. permissible		+85 (optional version	+125)		$^{\circ}$ C
21 Shaft bearings		sintered bearings			
22 Shaft load max.:					
– with shaft diameter		1			mm
– radial at 3 000 rpm (1,5 mm from bearing)		0,5			N
– axial at 3 000 rpm		0,1			N
– axial at standstill		20			N
23 Shaft play					
– radial	$\leq$	0,03			mm
– axial	$\leq$	0,2			mm
24 Housing material		steel, nickel plated			
25 Weight		13			g
26 Direction of rotation		clockwise, viewed from the front face			
<b>Recommended values - mathematically independent of each other</b>					
27 Speed up to	$n_{e \max}$	12 000	12 000	12 000	rpm
28 Torque up to	$M_{e \max}$	1	1	1	mNm

